

# Chapter (1): Introduction

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## 1.1) What is statistical mechanics?

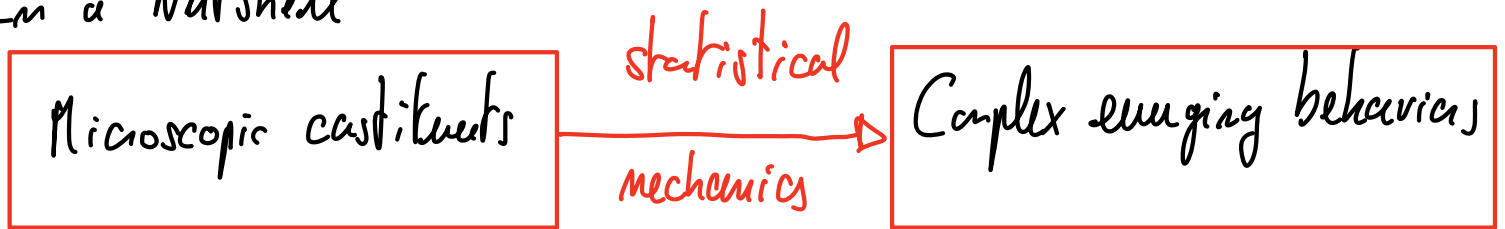
20<sup>th</sup> century, 3 scientific revolutions

→ quantum mechanics for the infinitely small (2022 Nobel prize on Bell inequalities)

→ relativity for the infinitely large (2017 Nobel Prize on gravitational waves)

→ statistical mechanics with the infinitely complex (2024 Nobel prize for neural networks)

In a Nutshell



Rather small number of atoms

emergence →

Very complex macroscopic world

Question: How do we account for this?

① "How is Different" Phil Anderson, 1972

A large number of particles can self-organize into states of matter with properties unmatched at the single-particle level

ex: Solid state can resist external forces

→ Does this mean that accounting for this diversity is hopeless? No, because

②

## II) Different is often the same

Many emerging phenomena look alike.

ex: Hexagonal packing in honeycombs, pineapple, Giant causeway, cell tissues (eye of flies), etc.

→ The recurrence of these patterns suggests the existence of underlying organizing principles. Deciphering them is the goal of statistical mechanics.

## III) More can also be simpler

\*Poincaré: 3-body problem is not solvable & classical mechanics with few degrees of freedom is very hard

\*  $1 \text{ m}^3$  of air  $\sim 10^{23}$  molecules  $\Rightarrow$  horribly complicated!

But  $T = 22^\circ\text{C}$ ,  $P = 1 \text{ bar}$ , Humidity = 50% are 3 numbers that suffice to characterize pretty well these  $\sim 10^{23}$  degrees of freedom.

→ emerging simplicity

Goal of statistical mechanics: Identify the microscopic details that are useless, eliminate them & construct self-contained theory that accounts for the emerging properties of a system.

Comments: This is generic and may apply outside physics: economy, epidemiology, computer science, sociology have research fields at the interface with statistical physics. Here: focus on particles.

## 1.2) Equilibrium statistical mechanics: the ensemble approach

Most laws of physics are dynamical: Maxwell's equations, Einstein's equation, Schrödinger's equation, etc.

⇒ Very complicated PDEs that predict the state of a system given the perfect knowledge of its state at an earlier time

### Two limitations

- ① Measuring the state of a system is very hard ( $N \sim 10^{23}$ )
- ② Solving these equations is very hard

### Ensemble approach

Do not even try, this is useless.

Instead, characterize the probability to find the system in a given state.

### Classical system

$N$  degrees of freedom  $(q_1, \dots, q_N, p_1, \dots, p_N) \equiv (\vec{q}, \vec{p})$

\* Prepare the system with some initial condition & let it evolve. Repeat  $N$  times

$$\vec{q}_i(0), \vec{p}_i(0) \xrightarrow{\text{evolution}} \vec{q}_i(t), \vec{p}_i(t) \quad ; \quad i \in \{1, \dots, N\}$$

\* Initial conditions not always the same

$$\int \delta(\vec{q}^0, \vec{p}^0, t=0) \underbrace{\prod_i dq_i dp_i}_{\equiv dP}$$

is the proba that initial condition is such that

$$q_i(t=0) \in [q_i^0, q_i^0 + dq_i] \text{ \& \& } p_i(t=0) \in [p_i^0, p_i^0 + dp_i]$$



$$\rho(\vec{q}, \vec{p}, t) dP$$

evolution of trajectories

the proba that, at time  $t$ ,

$$q_i(t) \in [q_i^0, q_i^0 + dq_i] \text{ \& \& } p_i(t) \in [p_i^0, p_i^0 + dp_i]$$

$g(\vec{q}^0, \vec{p}^0, t)$  is the **probability density** to find  $\vec{q}(t), \vec{p}(t)$  within a volume  $dP$  of  $\vec{q}^0, \vec{p}^0$  at time  $t$ . (4)

For simplicity, we drop the "0" superscript & write  $g(\vec{q}, \vec{p}, t)$ .  $\triangle$  Here  $\vec{q}$  &  $\vec{p}$  are fixed position & momenta, while  $\vec{q}(t)$  &  $\vec{p}(t)$  are solutions of Hamilton's equations...

Averages Consider some quantity  $O(\vec{q}, \vec{p})$ , that we refer to as an **observable**

We define the average of  $O$  at time  $t$  as

$$\langle O(t) \rangle = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N O(\vec{q}_i(t), \vec{p}_i(t)) \quad (1)$$

$$= \int d\vec{q} d\vec{p} \quad O(\vec{q}, \vec{p}) g(\vec{q}, \vec{p}, t) \quad (2)$$

Again, in (1),  $\vec{q}_i(t)$  &  $\vec{p}_i(t)$  are trajectories while in (2) they are fixed vectors.

If we have  $g(\vec{q}, \vec{p}, t)$ , then we can predict the values of  $\langle O(t) \rangle$  for any observable.

Statistical mechanics As  $t \rightarrow \infty$ , the probability density  $g(\vec{q}, \vec{p}, t)$

converges towards its **steady-state** value  $g_{ss}(\vec{q}, \vec{p}) = \lim_{t \rightarrow \infty} g(\vec{q}, \vec{p}, t)$ .

Equilibrium statistical mechanics Boltzmann, Gibbs & others guessed what

$g_{ss}$  is for a wide class of systems.

### 1.2.1) The microcanonical ensemble

Consider an isolated classical system characterized by a time independent Hamiltonian  $H(\vec{q}, \vec{p})$ .

Dynamics  $\vec{q}(t)$  &  $\vec{p}(t)$  solutions of  $\dot{\vec{q}}(t) = \frac{\partial H}{\partial \vec{p}}$  &  $\dot{\vec{p}}(t) = -\frac{\partial H}{\partial \vec{q}}$ , where  $\frac{\partial}{\partial \vec{q}} = \left(\frac{\partial}{\partial q_1}, \dots, \frac{\partial}{\partial q_N}\right)$  &  $\frac{\partial}{\partial \vec{p}} = \left(\frac{\partial}{\partial p_1}, \dots, \frac{\partial}{\partial p_N}\right)$ .

The energy  $E(t) = H(\vec{q}(t), \vec{p}(t))$  is a constant of motion

$$\frac{d}{dt} E(t) = \frac{\partial H}{\partial \vec{q}} \cdot \dot{\vec{q}}(t) + \frac{\partial H}{\partial \vec{p}} \cdot \dot{\vec{p}}(t) = 0 \quad (\text{Chain rule})$$

$\Rightarrow$  the dynamics takes place along the **energy surface**  $\{\vec{q}, \vec{p} \text{ s.t. } H(\vec{q}, \vec{p}) = E(t)\}$

Microcanonical hypothesis For a sufficiently complex system, the energy surface is visited uniformly & ergodically  $\Rightarrow$  All configurations with the same energy are visited with equal probability.

Microcanonical measure for discrete systems

Classical isolated system described by a set of configurations  $\{\varphi\}$ . Then, if the system is at energy  $E$ , its **microcanonical distribution** is

$$P_E(\varphi) = \frac{1}{\Omega(E)} \delta_{H(\varphi), E} \quad (1)$$

where: \*  $\Omega(E)$  is the number of configurations of energy  $E$

\*  $\delta_{a,b}$  is the KRONECKER delta, such that  $\delta_{a,b} = 1$  if  $a=b$  &  $\delta_{a,b} = 0$  otherwise